

# Pre-class Warm-up!!!

Let  $f, g, h$  be three functions  $\mathbb{R} \rightarrow \mathbb{R}$  and consider their values at 0, 1 and 2.

Which of the following are logically correct statements?

a. If  $f, g, h$  are linearly independent then so are the three vectors

Correct *Most*  
Incorrect *✓ some*

$$\begin{bmatrix} f(0) \\ f(1) \\ f(2) \end{bmatrix} \quad \begin{bmatrix} g(0) \\ g(1) \\ g(2) \end{bmatrix} \quad \begin{bmatrix} h(0) \\ h(1) \\ h(2) \end{bmatrix}$$

b. If  $f, g, h$  are dependent, then so are the three vectors

$$\begin{bmatrix} f(0) \\ f(1) \\ f(2) \end{bmatrix} \quad \begin{bmatrix} g(0) \\ g(1) \\ g(2) \end{bmatrix} \quad \begin{bmatrix} h(0) \\ h(1) \\ h(2) \end{bmatrix}$$

Correct *✓ More*  
Incorrect *fewer* | If  $af + bg + ch = 0$  *zero function*  
then  $a f(0) + b g(0) + c h(0) = 0$   
etc

c. If the three vectors  $\begin{bmatrix} f(0) \\ f(1) \\ f(2) \end{bmatrix}$   $\begin{bmatrix} g(0) \\ g(1) \\ g(2) \end{bmatrix}$   $\begin{bmatrix} h(0) \\ h(1) \\ h(2) \end{bmatrix}$  are linearly independent then so are  $f, g, h$ .

*✓ Correct*  
*Incorrect Most*

d. If the three vectors  $\begin{bmatrix} f(0) \\ f(1) \\ f(2) \end{bmatrix}$   $\begin{bmatrix} g(0) \\ g(1) \\ g(2) \end{bmatrix}$   $\begin{bmatrix} h(0) \\ h(1) \\ h(2) \end{bmatrix}$  are linearly dependent then so are  $f, g, h$ .

*Correct*  
*✓ Incorrect*

*c is the contrapositive of b so c is correct.*

*d* *a*

*We used c. last time with  $e^x, \sin x, 1$ .*

$$\text{so } a \begin{bmatrix} f(0) \\ f(1) \\ f(2) \end{bmatrix} + b \begin{bmatrix} g(0) \\ g(1) \\ g(2) \end{bmatrix} + c \begin{bmatrix} h(0) \\ h(1) \\ h(2) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

## Section 5.1: second order linear differential equations

## Section 5.2: higher order linear differential equations

These two sections do the same thing.

Vocabulary review:

- Linear, homogeneous differential equations
- Solution space, initial value problem
- Linearly independent solutions

New vocabulary

- superposition of solutions
  - characteristic equation
- = the solutions to a homogeneous equation form a vector space.*

We learn:

- The Wronskian
- Solutions of linear homogeneous d.e.'s form a vector space.
- How to use the characteristic equation to solve homogeneous equations with constant coefficients
- What to do about non-homogeneous equations: complementary functions.

Question 5 from Section 5.1 (like questions 3 and 10 on the HW).

Given two solutions

$y_1 = e^x$  and  $y_2 = e^{2x}$   
of the equation  $y'' - 3y' + 2y = 0$  homogeneous,  
linear, 2nd order  
find a particular solution with  
 $y(0) = 1$  and  $y'(0) = 0$

$y_1 = e^x$  and  $y_2 = e^{2x}$  are solutions

Here, all functions  $c_1 y_1 + c_2 y_2$   
where  $c_1, c_2$  are numbers are  
solutions. We find  $c_1, c_2$ .

Note:  $(c_1 y_1 + c_2 y_2)' = c_1 e^x + 2c_2 e^{2x}$   
 $c_1 y_1 + c_2 y_2 = c_1 e^x + c_2 e^{2x}$

Put  $x = 0$

$$c_1 + c_2 = 1$$

$$c_1 + 2c_2 = 0$$

$$c_1 = \frac{\begin{vmatrix} 1 & 1 \\ 0 & 2 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix}}$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$c_2 = \frac{\begin{vmatrix} 1 & 1 \\ 1 & 0 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix}}$$

$$c_1 = \frac{2}{1} = 2$$

$$c_2 = \frac{-1}{1} = -1$$

The particular solution is  
 $y = 2e^x - e^{2x}$

## Independence using the Wronskian

### Definition

Suppose we are given  $n$  functions  $y_1, \dots, y_n$   
Their Wronskian is the function

$$W(x) = \det \begin{bmatrix} y_1 & \dots & y_n \\ y_1' & \dots & y_n' \\ y_1'' & \dots & y_n'' \\ \vdots & \dots & \vdots \\ y_1^{(n-1)} & \dots & y_n^{(n-1)} \end{bmatrix}$$

Theorem (easy and useful part of bigger theorem)

If  $y_1, \dots, y_n$  are linearly dependent functions then  $W(x) \equiv 0$  (the zero function)

Proof: If  $c_1 y_1 + \dots + c_n y_n \equiv 0$  then  
 $c_1 y_1^{(r)} + \dots + c_n y_n^{(r)} \equiv 0$  for every  $r$ .  
The columns of the Wronskian matrix are dependent. Thus its det  $\equiv 0$

Corollary. If  $W(x) \neq 0$  then  $y_1, \dots, y_n$  are independent.

5.1 question 26 (like question 25)

Show that  $2\cos x + 3\sin x$ ,  $3\cos x - 2\sin x$  are independent.

Solution.

$$\begin{aligned} W(x) &= \begin{vmatrix} 2\cos x + 3\sin x & 3\cos x - 2\sin x \\ -2\sin x + 3\cos x & -3\sin x - 2\cos x \end{vmatrix} \\ &= (2\cos x + 3\sin x)(-3\sin x - 2\cos x) \\ &\quad - (-2\sin x + 3\cos x)(3\cos x - 2\sin x) \\ &= (-9 - 4)\sin^2 x + (-4 - 9)\cos^2 x + (-12 + 12)\sin x \cos x \\ &= (-13)(\sin^2 x + \cos^2 x) = -13 \neq 0 \end{aligned}$$

Thus the functions are independent.

Example done for section 4.7.

Are the functions  $e^x$ ,  $\sin x$  and  $1$  linearly independent?

Solution

$$W(x) = \begin{vmatrix} e^x & \sin x & 1 \\ e^x & \cos x & 0 \\ e^x & -\sin x & 0 \end{vmatrix}$$

$$= \begin{vmatrix} e^x & \cos x \\ e^x & -\sin x \end{vmatrix} = -e^x(\sin x + \cos x)$$

$$\neq 0$$

Thus the functions are independent.

# Pre-class Warm-up!!!

Which of the following statements did we prove last time?

Let  $y_1, \dots, y_n$  be functions of  $x$  and let  $W(x)$  be their Wronskian.

- ✓ a. If  $y_1, \dots, y_n$  are dependent then  $W(x)$  is identically zero.
- b. If  $W(x)$  is identically zero then  $y_1, \dots, y_n$  are dependent.
- c. If  $y_1, \dots, y_n$  are independent then  $W(x)$  is not identically zero
- ✓ d. If  $W(x)$  is not identically zero then  $y_1, \dots, y_n$  are independent
- e. We didn't prove any of these last time.

Can we even remember what the Wronskian is?

f. Are we comfortable making an adjective into a noun?

## Theorems about the existence of solutions

The following theorem combines  
from Section 5.1: Theorems 1, 4  
from Section 5.2: Theorems 1, 4.

Theorem. The solutions to the  $n$ th order linear d.e.

$$y^{(n)} + p_{n-1}(x)y^{(n-1)} + \dots + p_1(x)y' + p_0(x)y = 0$$

where  $p_0, \dots, p_{n-1}$  are continuous  
form a vector space of dimension  $n$ .

Theorem 2. For each number  $a$  and for all  
numbers  $b_0, \dots, b_{n-1}$ , there **is a unique**  
solution  $y$  with  
 $y(a) = b_0, y'(a) = b_1, \dots, y^{(n-1)}(a) = b_{n-1}$

Assuming theorem 2, prove theorem 1  
that the space of solutions has dimension  
 $n$ .

Take an independent set of solutions  
 $y = c_1 y_1 + \dots + c_r y_r$   
 $y_1, \dots, y_r$ . To get a solution satisfying  
the initial conditions we solve

$$\begin{bmatrix} y_1(a) & y_2(a) & \dots & y_r(a) \\ y_1'(a) & y_2'(a) & \dots & \vdots \\ \vdots & \vdots & \dots & \vdots \\ y_1^{(n-1)}(a) & \dots & \dots & y_r^{(n-1)}(a) \end{bmatrix} \begin{bmatrix} c_1 \\ \vdots \\ c_r \end{bmatrix} = \begin{bmatrix} b_0 \\ \vdots \\ b_{n-1} \end{bmatrix}$$

If there is a solution, it is unique.

This implies  $r \leq n$ . Now assume that  
 $y_1, \dots, y_r$  is a maximal independent set.  
It is a basis, and so  $y_1, \dots, y_r$  span the  
solution space. There always is a solution  
to the matrix equation, so  $r \geq n$   
We conclude  $r = n$ .

## Solving linear differential equations with constant coefficients: the characteristic equation

These look like  $ay'' + by' + cy = 0$  where  $a, b, c$  are numbers.

Look for solutions of form  $y = e^{rx}$   
 $y' = re^{rx}$        $y'' = r^2 e^{rx}$

Substitute

$$ar^2 e^{rx} + bre^{rx} + ce^{rx} = 0$$

$$e^{rx}(ar^2 + br + c) = 0$$

We get solutions when

$$ar^2 + br + c = 0$$

This is the characteristic equation.

Like Section 5.1 questions 33-42.

Find the general solution of the differential equation

$$y'' - 2y' - 3y = 0$$

Solution. The characteristic equation is  
 $r^2 - 2r - 3 = 0$        $(r-3)(r+1) = 0$

$$r = 3 \text{ or } r = -1$$

$y = e^{3x}$        $y = e^{-x}$  are solutions.

The general solution is

$$y = c_1 e^{3x} + c_2 e^{-x}$$



Like Section 5.1 questions 33-42.

Find the general solution of the differential equation

$$y'' + 4y' + 4y = 0$$

Solution: The characteristic equation is

$$(r^2 + 4r + 4) = 0 \quad (r+2)^2 = 0$$

$r = -2$ ,  $y = e^{-2x}$  is a solution,

When there is a repeated root like this we get another solution

$y = x e^{-2x}$  so the general

solution is  $y = c_1 e^{-2x} + c_2 x e^{-2x}$

Check  $y = x e^{-2x}$  is a solution

$$y' = e^{-2x} - 2x e^{-2x}$$

$$y'' = -2e^{-2x} - 2e^{-2x} + 4x e^{-2x}$$

$$\begin{aligned} y'' + 4y' + 4y &= -4e^{-2x} + 4x e^{-2x} + 4e^{-2x} - 8x e^{-2x} + 4x e^{-2x} \\ &= 0 \end{aligned}$$

## A stronger theorem about the Wronskian

Theorem. Suppose the  $n$  functions  $y_1, \dots, y_n$  are solutions of a homogeneous  $n$ th order linear d.e. with continuous coefficients of

$y, \dots, y^{(n-1)}$ .

- If they are dependent then their Wronskian is identically 0. *We did this already.*
- If they are independent then their Wronskian is never 0.

For a proof of b. using 'Abel's formula' see 5.1 question 32 and 5.2 question 35.

## Particular and complementary solutions

Like 5.2 questions 21-24

24. A non-homogeneous d.e., a complementary solution  $y_c$  and a particular solution  $y_p$  are given.

Find a solution satisfying the initial conditions:

$$y'' - 2y' + 2y = 2x, \quad y(0) = 4, \quad y'(0) = 8$$

$$y_c = c_1 e^x \cos x + c_2 e^x \sin x$$

$$y_p = x + 1$$

Explanation:

A complementary solution is a solution to the corresponding homogeneous equation. A particular solution is an actual solution.

The general solution has the form  $y_c + y_p$  where  $y_c$  is a general solution to the homogeneous eqn.

$$\begin{aligned} \text{Solve } y(0) &= y_c(0) + y_p(0) \\ &= c_1 + 1 = 4, \quad c_1 = 3 \end{aligned}$$

$$y' = y'_c + y'_p = c_1 e^x \cos x - c_1 e^x \sin x + c_2 e^x \sin x + c_2 e^x \cos x + 1$$

$$y'(0) = c_1 + c_2 + 1 = 8 \quad \text{so } c_2 = 4$$

The solution is

$$y = 3e^x \cos x + 4e^x \sin x + x + 1$$

## Non-homogeneous equations

$$\text{Let } y^{(n)} + p_1(x)y^{(n-1)} + \dots + p_n(x)y = f(x)$$

be a non-homogeneous  $n$ th order linear d.e.  
The associated homogeneous equation is the same, with 0 on the right instead of  $f(x)$ .

Suppose the  $p_i$  are continuous.

Theorem 5.

Let  $y_p$  be a (particular) solution of the non-homogeneous equation, and let  $y_1, \dots, y_n$  be a basis for the solution space of the associated homogeneous equation.

Then every solution of the non-homogeneous equation can be written

$$y_p + y_c$$

where  $y_c = c_1y_1 + \dots + c_ny_n$  is a solution of the associated homogeneous equation.

Reason if  $y$  is a solution then  $y - y_p$  solves the homogeneous equation, so  $y - y_p = y_c$   
 $= c_1y_1 + \dots + c_ny_n$ .  
and  $y = y_p + y_c$ .

What is the general solution to the equation  $y'' - y = 0$ ?

a.  $c_1 e^{2x} - c_2$

b.  $c_1 x^2 + c_2 x$

c.  $c_1 e^x + c_2 x e^x$

✓ d.  $c_1 e^x + c_2 e^{-x}$

e. None of the above.

where  $c_1, c_2$  are constants.

$$r^2 - 1 = 0 \quad r = \pm 1$$